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Differences Between EDCRASH and CRASH3

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Differences Between EDCRASH and CRASH3

Terry D. Day and Randall L. Hargens Engineering Dynamics Corp.

ABSTRACT

Motor vehicle accident researchers have used the CRASH computer program for some time. the years, the code was upgraded until it reached its present and popular form, CRASH3, which runs on a mainframe computer or minicomputer with a sizeable memory capacity. A new version of the program, EDCRASH, has been developed which runs on personal computers using 128K of memory. This paper describes and compares this program with its mainframe counterpart. The program performed the same function as CRASH3, but was designed as a screen-oriented program utilizing the environment of the personal computer. Its design also allowed for file saving, graphics, routing of output, and interfacing with other accident reconstruction programs. For most accident types, the results for both programs were identical. However, for some types the results were different.

THE CRASH (CALSPAN RECONSTRUCTION of Accident Speeds on the Highway) computer program has been used as an effective tool for motor vehicle accident investigation for many years. Since its development in the early seventies [1-6], it has undergone many revisions and These changes have included refinements. debugging the code itself and modifications to improve its accuracy. It is doubtful that any computer program for use by accident investigators has received so much attention, undergone so thorough an evaluation, and provided so much useful data for those people who are concerned about highway accidents and their effect on our society.

HISTORY AND PURPOSE OF CRASH

Since 1979, the National Highway Traffic Safety Administration (NHTSA) has implemented the CRASH program in a recent version, called CRASH3, for use by the National Accident Sampling System (NASS). Using a nationwide network of accident investigators, NASS has been developing a statistical database for the purpose of finding out what kind of accidents are the greatest threat to our society [7]. Automotive researchers have been able to use CRASH to provide collision dynamics for typical impact configurations in order to assess the effects upon occupant dynamics. This, in turn, aids vehicle designers who can use the results to build safer cars. Accident investigators use the program to help determine accident causation. Recently, the CRASH program has been used in the field of civil and criminal litigation, where it is an effective tool which can provide answers to technical accidentrelated questions.

PURPOSE OF THIS PAPER

This paper describes a recent version of the CRASH program called EDCRASH (Engineering Dynamics Corporation Reconstruction of Accident Speeds on the Highway). Its purpose is to compare EDCRASH with CRASH3, the version upon which it was based. First, similarties between the programs will be established. Then, because the major intent of this paper is to identify the differences between EDCRASH and CRASH3, those differences will be studied in the form of examples which illustrate the differences and their effect upon the results. Accident investigators familiar with CRASH3 can use this information to become familiar with EDCRASH. Others will become familiar with the general scope of either program.

^{*}Numbers in brackets designate references at the end of the paper.

OVERVIEW

The CRASH program provides a reconstruction of single- and two-vehicle accidents. The user supplies information gained from accident site and vehicle inspections. The program uses this information to determine the conditions at impact. The speed of the vehicle(s) at impact is produced only if scene data (impact/rest positions and path data) is supplied. Otherwise, the results are limited to speed change (a measure of impact severity). The program also produces intermediate results, such as separation velocities, energy absorbed by damage, and parameters associated with a trajectory simulation.

The results provide a consistent and well-validated methodology for the reconstruction of motor vehicle accidents. In addition, the program is a useful means of performing repeated analyses to test different accident scenerios (this is refered to as a "what if" analysis).

PROCEDURE

In order to provide a direct comparison between the programs, a version of CRASH3 dated December, 1981, was purchased from Mcauto (McDonnell Douglas Automation Co.) and compiled and executed on Boeing Computer Services' CDC-Cyber mainframe computer. EDCRASH, Version 2.0, dated July, 1984, provided the results on an IBM Personal Computer. Accessories included a 320K RAMdrive, IBM color/graphics adapter, and Epson MX-100 printer. Two different input data sets were supplied to each program and the results were examined. Various program options were exercised in order to evaluate conditions which led to different results. Similiarities and differences were then reported.

SIMILARITIES

EDCRASH and CRASH3 programs required the same input and yielded the same output. This was a major objective of program design, since researchers using both programs may be contributing to the same database.

Both programs were interactive. The user responded to questions (up to 50) requested at the terminal (either CRT or line printer). The input required quantitative data in three general categories. These were: (1) General Vehicle Data, (2) Accident Site Data, and (3) Vehicle Damage Data.

The General Vehicle Data defined vehicle dimensional and inertial properties and the relationship (mutual orientation) of the vehicles at impact. The Accident Site Data identified vehicle positions at impact, vehicle positions at rest, and how the vehicles moved from impact to rest (skidding, spinning,

braking, and tire/ground friction). The Damage Data supplied the measured location and profile of vehicle damage.

Not all questions required answers. Some had default answers and some only provided additional detail. A list of input questions can be found in the examples cited later in this paper. A description of each of the input data questions was beyond the scope of this paper. For such a description, the reader is referred to the literature [8,9].

The output session began with a display of error messages. These messages were categorized as either informative or fatal. In the latter case, execution was terminated and output was limited to damage-based results.

The form of the output was either complete or abbreviated. The complete form displayed the impact speed and speed change for both vehicles, followed by an echo of impact and separation conditions, trajectory simulation results, summary of damage data, and vehicle dimensional and inertial properties. The abbreviated results were limited to a summary of impact speeds and speed changes, and trajectory simulation results.

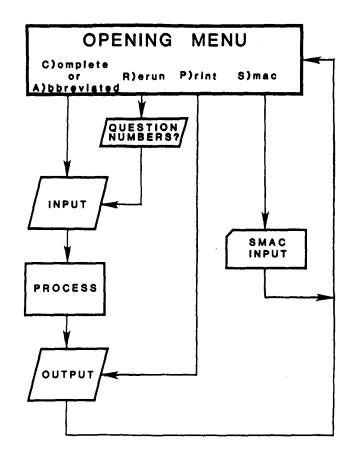


Figure 1 - Flow diagram for CRASH3

DIFFERENCES

The differences between EDCRASH and CRASH3 were found primarily in three areas: (1) User interactivity, (2) Calculations, and (3) Graphics.

User Interactivity

CRASH3 was coded in FORTRAN for use on remote input data terminals, usually connected to a mainframe computer. The terminal was a CRT or local line printer. In either case, the input questions and output results scrolled continuously, one line at a time.

EDCRASH was coded in compiled BASIC for use on the IBM PC or IBM compatible personal computer. As a result, the user interfaced with the program in a substantially different manner. This may be illustrated by inspection of flow diagrams for CRASH3 (figure 1) and EDCRASH (figure 2).

A CRASH3 session began at a menu which provided the user with a list of program options:

COMPLETE - The program ran through its entire cycle. All of the input questions and output results were presented in their most detailed formats.

ABBREVIATED - The program ran through its entire cycle. The input/output was presented in a concise format.

RERUN - The program was re-executed after changing the input for up to 12 questions (followed by processing and new results).

PRINT - Printed a Complete listing of the results.

SMAC - Generated an input data set for the SMAC (Simulation Model of Automobile Collisions [10]) program based on the CRASH3 results.

 $\ensuremath{\mathsf{END}}$ – Returned to the computer operating system.

The user initiated a CRASH3 run by selecting the type of run to be performed. a complete run was requested, then all questions were displayed in a long and rather detailed (complete) form. If an abbreviated form was requested, the input questions were presented in a concise form. The user's memory could be refreshed by entering a ?, which caused the complete form of the question to be When the input session was displayed. concluded, the results were processed and the output was displayed. After each execution, the program returned to the menu, allowing the user to run an abbreviated program or rerun

with modified input, view the results, and follow up with input data changes and/or a complete form of the output listing. The user could then generate a SMAC input data set and exit the program. (The SMAC program can be used to test the CRASH results.)

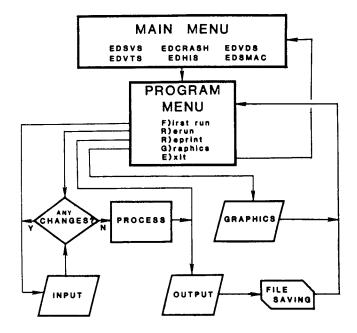


Figure 2 - Flow diagram for EDCRASH

EDCRASH was one of a series of six accident reconstruction programs, all of which were displayed on a Main Menu. Execution was initiated by selecting EDCRASH from the Main Menu. The session began with a display of the Program Menu, which provided the user with a list of options:

FIRST-RUN, INTERACTIVE SESSION - Began the question/answer session in the abbreviated format. The complete form of any question was displayed at the bottom of the screen, along with the required answer format and sample answer, if a ? was entered.

RERUN WITH INPUT FROM A PREVIOUS SESSION - Initiated the rerun option, which required the user to supply an input file (the previous file was the default file; otherwise, any previously-saved input file could be supplied). The session began by asking which section of input required review and/or changes.

OUTPUT FROM A PREVIOUS SESSION - Redisplayed the output, which required the user to supply an output file (the previous session was the default file; otherwise, any previously-saved file could be supplied). The session began by asking for the desired form of output (complete or abbreviated) and routing (screen or printer).

PICTORIAL DISPLAY OF ACCIDENT SITE - Created a pictorial representation of the accident site, which also required the user to supply an output file.

EXIT TO MAIN MENU - Returned to the Main Menu in order to execute another program or exit to the operating system.

The user initiated the analysis by selecting the type of run to be performed. However, since EDCRASH had a file-saving option, three additional options were available when initiating a session. By appropriately selecting (1) rerun with previous input, (2) reprint previous output, or (3) pictorial display of accident site, the user could rerun, reexecute, or review the results of previous sessions without re-entering the input data.

When a first-run was requested and the input session was complete, or if a rerun was requested, EDCRASH asked the user if a review of the input data, or "Any Changes?", was desired. If so, the user could scan each of the sections of data (General, Scene, Impact to rest, Tire/road, and Damage) and accept the data or change it prior to execution. Processing was initiated by a negative response to "Any Changes?". Differences in processing may be found in a later section of this paper.

At the completion of the output session, EDCRASH allowed the user to save the input and/or output files, and then returned to the Program Menu for another run.

At this point, the user could perform a new run, rerun, reprint, graph, or terminate execution. If an EDSMAC input file was desired, it was not necessary to create one, since an EDCRASH output file structure was identical to an EDSMAC input file structure.

Calculations

RICSAC data sets, used during the development of CRASH [5], were used to demonstrate the calculations. RICSAC8 was used to provide typical input and output and establish a valid basis for results. Then, RICSAC7 was used to demonstrate the effects due to some coding differences.

The RICSAC8 input data, shown in figure 3, described an impact between two Chevrolet Chevelles. Vehicle #1 struck vehicle #2 at the passenger-side door. The angle of impact was 90 degrees (perpendicular). Both vehicles responded to impact by spinning clockwise while coming to rest. In order to process the input, the CDC-Cyber required approximately 1 second; the IBM required 5.2 seconds.

Figure 3 - RICSAC8 input data set

The computation results for CRASH3 are shown in figure 4 and the results for EDCRASH are shown in figure 5. All the results were shown (i.e., the "Complete" form was selected) in order to illustrate all the differences in output.

Neither program generated any warning messages and the results were indentical. EDCRASH reported some additional information, including Energy Absorbed by Damage, Magnitude of Principal Force, and Moment Arm of Principal Force, in the SUMMARY OF DAMAGE DATA.

After the preliminary output was reviewed, a rerun was performed and a trajectory simulation was requested. The response time for the CDC-Cyber was 4.5 seconds. The processing time for the IBM was 375.4 seconds. For purposes of brevity, only the abbreviated results were displayed.

Inspection of the output results (CRASH3, figure 6; EDCRASH, figure 7) revealed a difference in IMPACT SPEEDS AND SPEED CHANGES. The difference was due to an increase in the integration time interval. While CRASH3 used an interval of 0.025 seconds, EDCRASH used

SUMBARI OF CRASHS RESULTS

RICSAC #8 CHEVELLE VS CHEVELLE

VEHICLE # 1

	IMPACT SPEED MPH		5í	EED CHAI	BASIS OF	
•	FWD	LAT	TOTAL	LONG.	LATERAL	RESULTS
	16.7		12.6	6.9	10.5	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR HOMENTUM
	,					 SPINOUT TRAJECTORIES AND DAMAGE
•			11.8	-8.5	8. 3	DAMAGE DATA ONLY

VEHICLE # 2

511	CMCACT SHEED MEH		EEU CHAI	46E	BASIS OF	
FWD	LAT	TOTAL	LONG.	LATERAL		
25.7	, ø	12.0	10.0	-6.6	SFINGUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM	
	•				SPINOUT TRAJECTORIES AND DAMAGE	
		11.2	-7.9	-7,9	DAMAGE DATA ONLY	

SCENE	INFORMAT	I DH

IMPACT X FOSITION	- 10, 90	FT.	. 00	FT.
IMPACT Y POSITION	3.20		1.90	FT.
IMPACT HEADING ANGLE		DEG.	89.99	D€G.
FEST X-FUSITION	. 54	F1.	6.50	FT.
BEST Y-FOSITION	12.00	FT.	21.00	FT.
REST HEADING ANGLE	45.99	DEG.	140.98	DEG.
DIRECTION OF ROTALION	CW		E₩	
AMOUNT OF RUTATION	36£		360	

VEHICLE # 1

VEHICLE # 2

7411001111						
			COLLISIO	ONDITIONS		
VEHICLE # 1				VEHICLE # 2		
xC101	==	-10.9	FT.	XC20.	=	.0 FT.
YC 1811	*	5.2	FT.	1C20'	=	1.9 FT.
PS110	=	. 0	DEGMEES	PSI2Ø	-	90.0 DEGREES
ครบบซ้	20	. 4	DEG SEC	FSI2DØ	=	.⊯ DEG/SEC
BETAL	=	٥.	DEGREES	BETAS	*	.Ø DEGREES
			ON CONDITIONS			
xCS1	=	16.9	FI	xC52`	_	.ю FT.
7C51				YCS21		1.9 FT.
	-	. 6		PS152	=	90.0 DEG
051	_	9.8		USZ		15.7 MPH
VSI	-	10.5		VS2	=	-6.6 MPH
FS1SD1			DEG/SEC	FSISD2	œ	54.5 DEG/SEC

Figure 4 - CRASH3 results with RICSAC8 input

```
IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORMATO LATERAL
VEHILL 18.7 MFH ... WEHL
VEHILL 25.7 MFH ... WEHL
VEHILL 25.7 MFH ... WEHL
 SEELD CHANGE (DAMAGE)
TOTAL LONG.
VEHWL 11.8 MEH 8.3 MEH
VEHW2 11. MEH 7.9 MEH
| SFEED CHANGE (LINEAR MOMENTUR) | 1014L | LONG. | LA1. | VEH#1 | 12.6 MFH | 6.9 MFH | 18.5 MFH | VEH#2 | 12.8 MFH | -18.8 MFH
ENERGY DISSIPATED BY DAMAGE VEH#1 38479.3 FT-LB VEH#2 31220.8 FT-LB
                                                                                                                     RELATIVE VELOCITY DATA
SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEHME1 16.6 MF/H
VEHME2 5.0 MF/H
SPEED ORTHOG. 10 CG LINE (LINEAR MOMENTUM)
 CLOSING VELOCITY (LINEAR MOMENTUM)
19.7 MPH
                                                                                                                                                                                            (* INDICATES DEFAULT VALUE)
  SUMMARY OF DAMAGE DATA
                                                                                                                                                                                                                                                 VEHICLE # 2
                                                            VEHICLE # 1
DIMENSIONS AND INERTIAL PROPERTIES
                                                                                                                                                                                                                                                = 54.7 INCHES
= 59.2 INCHES
= 61.8 INCHES
= 45660.7 LD-SEC**2-IN
= 12.19 / LB-SEC**2-IN
= 98.8 INCHES
= 114.0 INCHES
= 36.*
                                              = 54.7 INCHES
= 59.2 INCHES
= 61.8 INCHES
= 43364.7 LB SEC**2 IN
= 11.592 LB SEC**2/IN
= 78.8 INCHES
= 114.9 INCHES
= 38.5 INCHES
                                                                                                                                                                                                          A2
B2
TR2
I2
M2
XF2
XR2
YS2
                                                                                                           ROLLING RESISTANCE
                                                                                                                                                                                                                                                         VEHICLE # 2
                VEHICLE # 1
                                                                                                                                                                                                                                      MI.----
                                                                                         - 87
```

Figure 4 (continued)

0.100 seconds, mainly to reduce processing time. This decision was supported by the fact that CRASH2 also used a 0.100 second interval. For most results, the effect of this change was less than 0.3 mph.

The RICSAC7 data, selected in order to demonstrate the effects of some minor coding errors and additional diagnostic error messages, is shown in figure 8. This data described an impact between a Chevrolet Chevelle (Vehicle #1) and a Volkswagen Rabbit (Vehicle #2). The Chevelle struck the Rabbit at the passenger-side door. The angle of impact was 120 degrees (slighlty more than perpendicular). The Rabbit responded by spinning clockwise and rolling a short distance before coming to rest. The Chevelle was redirected by the force of impact, but continued along an essentially straight course, without spinning, to its rest position.

SUMBAR, OF EDCRASH RESULTS

ENGINEERING DYNAMICS CORFORATION Date 12-06-1984 Fime 11:02:44 SAMPLE KUN RICSAC CASE #8 11/26/80

WARNING MESSAGES: NO MESSAGES

VEHTCLE	1

SF.	IMPACT SPEED MPH		SPEED CHAN	: BASI5 : O≠	
FWD	LAT	TOTAL	LONG.	LATERAL	RESULTS
16.7	0.0	12.6	6.7	10.5	: SPINOUT TRAJECTORIES AND : CONSERVATION OF LINEAR : HOMENTUM
0.0	0.0	a.a	0.0	۵.۵	: SPINOUT TRAJECTORIES AND : DAMAGE
		11.8	8.3	8.3	DANAGE DATA ONL

VEHICLE # 2

IMFACT : SPEED : MPH :		1	SF	SFEED CHANGE :			;	BASIS OF	
FWD	LAT	1 1	OTAL	LONG.		ATERAL	:	RESULTS	
25.7	ø.ø		12.0	10.0		6.6	ì	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM	
0.0	ø.ø	:	0.0	0.0		0.0	:	SPINOUT TRAJECTORIES AND DAMAGE	
		:	11.2	7.9	1	7.9	:	DAMAGE DATA DINLY	

SCENE INFORMATION

	VEHICLE	#1	VEHICLE	#2
IMPACT X-POSITION	10.90	FT.	0.00	FT.
IMPACT Y POSITION	3.20	FT.	1.90	FT.
IMPACT HEADING ANGLE	છ. જોઇ	DEG.	89.97	DEG.
RES) x FOSITION	ø. 5ø	ET.	6.5ñ	FT.
REST Y POSITION	12.00	FT.	21.00	FT.
REST HEADING ANGLE	45.79	DEG.	140.78	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF ROTATION	360		368	

IMPACT INFORMATION

	VEHICL	E #1	VEHICLE	#2
IMPACT X-POSITION	10.7	FT.	4.0	FT.
IMPACT Y PUSITION	5.2	FT.	1.9	⊦T.
IMPACT HEADING ANGLE	10.10	DEG.	90.0	DEG.
IMPACT ANGULAR ROTATION RATE	0.0	DEG/SEC	0.0	DEG/SEC
IMPACT SIDESLIP ANGLE	и.и	DEG.	0.0	DEG.
SEPARATION : PUSITION	10.2	FT.	3.0	FT.
SEFARATION Y FOSITION	3.2	FT.	1.7	FT.
SEPARATION HEADING ANGLE	0.0	DEG.	70.0	DEG.
SEPARATION FORWARD VELOCITA	9.B	MPH	15.7	MPH
SEPARATION LATERAL VELOCITY	19.5	HELL	0.4	MPH
SEFARATION ANGULAR ROTATION RATE	50.2	DEG/SEC	54.5	DEG SEC

INFACT SPEED CHARGECTORS AND CONSERVATION OF LINEAR MOMENTUMS FORWARD LATERAL

VEH		15.7 MER 25.7 MER		
	SFELI	CHANGE	(DAMAGE)	1.

		TOTAL	LONG.	141.	ANG.
VEH	#1	11.8 MPH	-8.3 MFH	8.3 MPH	~45.₩ DEG
VEH	#2	11.2 MFH	-7.9 MPH	-7.9 MFH	45.0 DEG.
	cere	D CHANCE (L.I.)	IEAR MOMENTUM)		

	SPEED	IDTAL	LOP		LA	T.	41	16.	
VEH VEH		12.6 MFH 12.0 MFH		MFH MFH	6.5		-56.6 33.4		

ENERGY DISSIPATED BY DAMAGE: VEH #1 - 38479.0 FT-LB VEH #2 - 31228.9 FT-LB

RELATIVE VELOCITY DATA

SPEED ALONG LINE THRU CGS (LINEAR NOMENTUM)
VEH #1 16.5 MFH
VCH #2 3.0 MPH

SPEED ORTHOG, TO CG LINE (LINEAR MOMENTUM)
VEH #1 2.0 NFH
VEH #2 25.5 MFH

CLOSING VELOCITY (LINEAR MUMENTUM) 19.5 MEH

Figure 5 - EDCRASH results with RICSAC8 input

	VEHICLE #1	VEHICLE #2
EGOF :	4	4
	4479.0 LBS.	4710.0 LDS.
	11FDEW1	Ø2RYEM2
	73.Ø IN.	84.5 IN.
	2.7 IN.	6.2 IN.
	T A IN	G 7 IN

CLASS (SIZE) CATEGOR:	4	4
WEIGH1	44/7.0 LBS.	4710.0 LDS.
CDC	11FDEW1	#2RYEN2
DAMAGE WIDTH	73.Ø IN.	84.5 IN.
CRUSH DEPTH 1	2.7 IN.	4.2 IN.
CRUSH DEPTH 2	3.6 IN.	B. 3 IN.
CRUSH DEPTH 3	#.# IN.	9.2 IN.
CRUSH DEPTH 4	W. W IN.	5.9 IN.
CRUSH DEPTH 5	0.0 IN.	4.4 IN.
CRUSH DEFTH 6	0.0 IN.	Ø. 8 IN.
DAMAGE MIDPOINT OFFSET	0.0 IN.	15.0 IN.
DAMAGE ENERGY	38479.3 FT. LB.	31220.9 FTLB.
MAGNITUDE OF PRINCIPAL FORCE	477.6.9 LD.	54794.6 LB.
DIRECTION OF PRINCIPAL FORCE	-45.0 DEG.	45.0 DEG.
MOMENT ARM OF PRINCIPAL FORCE	70.0 IN.	19.2 IN.
DAMAGE CENTROID	1.7 IN.	7.8 IN.

DIMENSIONAL, INERTIAL AND TIRE/ROAD PROPERTIES

	AFHICLE #1	VEHICLE #2
CG TO FRONT AXLE	54.7 IN.	54.7 IN.
CG TO REAR AXLE	59.2 IN.	59.2 IN.
TRACE WIDTH	61.8 IN.	61.8 IN.
YAW MUMENT OF INERTIA	43364.2 LB-SEC 2 IN	45480.7 LD-SEC 2 IN
MASS	11.6 LB-SEC^2/IN	12.2 LB-SEC*2/IN
BODY LENGTH FROM CG TO FRONT	98.8 IN.	98.8 IN.
BODY LENGTH FROM CG TO REAR	-114.0 IN.	114.0 IN.
BODY WIDTH	27.0 In.	77.0 IN.
	ROLLING RESISTANCE	
RIGHT FRONT TIRE	A 18.1	9.41

RIGHT FRONT TIRE	A. #1	0.01
LEFT FRONT TIRE	Ø.Ø1	0.61
RIGHT REAR TIRE	0.20	a. 20
LEFT REAR TIRE	0.20	6.20
TIRE ROAD PRICTION	₽.87	₩.87

Figure 5 (continued)

SUMMARY OF CRASH3 RESULTS

```
RICSAC #8 CHEVELLE VS CHEVELLE
```

IM	FORWARD	(TRAJECTORY AND	CONSERVATION	OF LINEAR MOMENTU
/Eli#1	19.3 MFH	.a mru		
/EH#2	21.8 MFH	.e MPH		
SF1	EED CHANGE	(DAMAGE)		
	TOTAL	LONG.	LAT.	ANG.
/EH#1	11.8 MFH	B. D MFH	B. 3 MFH	45.0 DEG.
/EH#?	11.2 MEH	T. C. MPH	- '.9 MEH	45.0 DEG.

	TOTAL	LONG.	LAT.	ANG.	
VEH#1	18.1 MFH	-15.9 MH	B.5 MFH	28.2 DEG	
VUH#2	17.2 MEH	B.1 MFH	-15.1 MPH	61.0 DEG	•
ENERGY	DISSIFATED	BY DAMAGE VI	H#1 38479.3	FT-LB VEH#	2 31220.8 FT L
SFEED A	ALONG LINE II	HRU COS (LINE	EAR MOMENTUM)		
VEH	11 19,21	MPR			
VEH	12 2.6 1	MF:11			
SFEED (ORTHOG. TO C	G LINE (LINE)	AR MOMENTUM:		
VEHA	11 2.34	4F11			
VEHI	21,71	MPH			
CLOSINO	VELUCITY (LINEAR MOMEN	TUM)		
	21.7 (MFH			

MAJECTORY SIMULATION PESULTS

++++	AEHIL LE	# 1 DID	T OU	CUNVERGE	++++		
* 1 * *	VEHICLE	# 2 DID	NOT	CONVERGE	++++		
NEUNS	(1) =	5			NRUNS (2)	=	5
CINI		. ø87			E2(1)	=	. 276
E1 (2)	=	. 666			E2(2)	*	. 000
E1 (3)	=	. 257			E2 (3)	=	. 155
E1(4)	=	. 000			E2(4)	=	. 000
E1 (5)	-	. ામકોલ			E2 (5)	77	. 666
OMITH	=	. 347			OMIN2	×	. 231

Figure 6 - CRASH3 results for RICSAC8 with a trajectory simulation

```
SUMMARY OF EDURASH RESULTS
ENGINEERING DYNAMICS CORPORATION Date 12:06-1984 frme 11:10:14
SAMPLE RUN RICSAL CASE #8 11/26/80
WARNING MESSAGES: NO MESSAGES
 IMPACT SPEED CHRATECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FURWARD LATERAL
VEH W1 19.1 MRH 0.0 MRH
VEH W2 22.1 MRH 0.0 MRH
      SPEED CHANGE (DAMAGE)
  70TAL LONG.
VEH #1 11.0 MEH B.7 MEH
VEH #2 11.2 MEH 7.9 MEH
                                          LONG.
  SPEED CHANGE (LINEAR MOMENTUM,
TOTAL LONG,
VEH #1 18.0 MEH 15.8 MEH
VEH #2 17.1 MEH 8.2 MEH
                                                            LAT.
8.7 MPH
-15.0 MFH
                                                                                      28.7 DEG.
61.3 DEG.
 ENERGY DISSIPATED BY DAMAGE: VEH #1 38479.3 FT-LD VEH #2
                                                                                                        31220.9 FT-LB
                                               RELATIVE VELOCITY DATA
  SFEED ALONG LINE THRU CGS (LINEAR HOMENTUM)
VEH #1 19,0 MPH
VEH #2 2.6 MPH
  SPEED ORTHOG. TO CG LINE GLINEAR MOMENTUM)
VEH #1 2.5 MPH
VEH #2 21.9 MPH
 CLOSING VELOCITY (LINEAR MOMENTUM) 21.6 MFH
                                               TRAJECTOR: SIMULATION RESULTS
  MENTOLE #1
                                                                                                 VEHICLE #2
 FRUMDER OF RUNS (MAXIMUM OF 5)
FIRST POSITION OF CREAM ( = .10)
FROM OF ROTATION X Y ERROR ( = .15)
FROM OF ROTATION XY ERROR ( = .19)
FROM OF ROTATION HEADING ERROR ( = .19)
FROM OF ROTATION HEADING ERROR ( = .15)
FROM OF ROTATION HEADING ERROR ( = .15)
FROM OF ROTATION HEADING ERROR ( = .15)
```

Figure 7 - EDCRASH results for RICSAC8 with a trajectory simulation

In order to process the input for RICSAC7, the CDC-Cyber computer required approximately 1 second; the IBM PC required 3.9 seconds.

The computation results for CRASH3 are shown in figure 9 and the results for EDCRASH are shown in figure 10. The complete form of output is shown in order to illustrate all the differences.

CRASH3 did not display any warning messages. EDCRASH generated two warning messages, both informative (i.e., non-fatal). The first message (refer to figure 10) told the user of an inconsistency in the damage data: Since the damage data (user-measured and table-supplied) for each vehicle was totally independent, but the vehicles' response had to obey Newton's three laws of motion, this was a check of consistency for vehicle damage data for both vehicles. The error message generated by EDCRASH indicated the force required to cause the observed (measured) damage for each vehicle was very dissimilar (the difference was

Figure 8 - RICSAC7 input data set [5]

greater than 100%). The source of the error was either (1) incorrect interpretation and/or measurement of damage, or (2) inappropriate stiffness data used by the program. The cause of the error should be identified, either by close inspection of the damage measurements or the vehicle crush stiffness parameter(s).

The second warning message issued by EDCRASH informed the user that an adjustment of vehicle separation velocities was performed in order to satisfy an assumption common to both programs: The regions of each vehicle which contact one another during the collision must reach a common velocity just prior to separation. The separation velocity for each vehicle was determined independently during the post-impact phase calculations. If the input data (impact/rest/end of rotation/point on curve positions, tire-ground friction, and wheel lock-ups) were perfect - and if the 3-degree of freedom model were exact - then the velocity (speed and direction) of the regions of contact would be exactly the same for both

RICSAC #7 CHEVELLE VS RABBIT

VEHICLE # 1

IMPACT SPEED MPH		ş:	PEED CHAI MPH	NGE	BASIS
FWD	LAT	TOTAL	LONG.	LATERAL	OF RESULTS
26.2		15.0	13.5	6.5	SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
	•				SPINDUT TRAJECTORIES AND DAMAGE
		19.7	-17-1	9.9	DAMAGE DATA ONLY

VEHICLE . 2

INFINCT SPEED MPH		SI	PEED CHAI	NGE	RASIS
FWD	LAT	TOTAL	LONG.	LATERAL	# OF # RESULTS
34.9	. 0	32.7	-27.0		* SPINOUT TRAJECTORIES AND CONSERVATION OF LINEAR MOMENTUM
				•	• SFINOUT TRAJECTORIES AND • DAMAGE
		43.0	-37.2	-21.5	* DAMAGE DATA ONLY

SCENE INFORMATION

	VEHICLE #	1	VEHICLE #	2
IMPACT X-POSITION	. 00	FI.	10.70	FT.
IMPACT Y POSITION	. 99	FT.	3.45	FT.
IMPACT HEADING ANGLE	. 99	DEG.	119.99	DEG.
REST X POSITION	84.50	FT.	22.90	FT.
REST Y-POSITION	18.28	FT.	41.48	FT.
REST HEADING ANGLE	16.50	DEG.	261.97	DEG.
END-OF-ROTATION X-FOSITION	. 00	FT.	22.00	FT.
END-OF-ROTATION V-FOSITION	. 1848	FT.	30.00	FT.
END-OF ROTATION HEADING ANGLE	. 66	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CM		CW	
AMOUNT OF ROTATION	366		360	

COLLISION CONDITIONS

VEHICLE # 1			VEHICLE # 2					
4C10'	-	. a	rt.	40201	=	1.5.	FT.	
VC10	-	. 0	FI.	ACCN.		3.4	FT.	
FSI1#	=	. 10	DEGREES	FS120	4	120.0	DEGREES	
PSI1D#	*	.0	DEG/SEC	FS12De	9	. 10	DEG/SEC	
BETAI	•	. 19	DEGREES	DETAT	-	. e	DEGREES	
			SEPARA (10	BH CONDITIONS				
4CS1"	-	.0	FT.	4C\$1;*		10.7	FT.	
YCSI'	*	. 13	FT.	YC521	=	3.4	FT.	
F9151	=	. и	DEG	PSIS2	4	120.0	DEG	
USI	320	12.	MEST	USP		8.0	MPH	
75 t	-	4.5	HEH	vs.	-	18. →	UCH	
F51501	=	. 69	DE G / SEC	FS1SD2	4	145.1	DEC SEC	

Figure 9 - CRASH3 results with RICSAC7 input

```
IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD LATERAL
    | SPEED CHANGE (LINEAR MOMENTUM) | TOTAL | LONG. | UNIT | LONG. | LONG
                                                                                                                                                                                            6.5 MPH
     ENERGY DISSIPATED BY DAMAGE VEH01 23188.8 FT-LB VEH02 196486.9 FT-LB
                                                                                                                                    RELATIVE VELOCITY DATA
  SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEH01 24.9 MPH
VEH02 7.3 MPH
SPEED ORTHOG, TO CG LINE (LINEAR MOMENTUM)
VEH01 -8.0 MPH
VEH02 -34.2 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
32.2 MPH
     SUMMERY UF DAMAGE DATA
                                                                                                                                                                                                                 * INDICATES DEFAULT VALUE)
                                                                       VEHICLE # 1
                                                                                                                                                                                                                                                                           VEHICLE # 2
 UTHENSIONS AND INERTIAL PROPERTIES.
                                                  - 54.7 INCHES
- 59.2 INCHES
- 61.8 INCHES
- 58872.2 LB SEC++, III
- 98.50 it there, III
- 114.4 INCHES
- 114.5 inches
                                                                                                                                                                                                                                                                                                                   PORT CONTRACTOR AND ADMIN
                 SETTLE # 1
                                                                                                                                                                                                                                                                             VEHICLE # 2
                                                                                                                                                                                                                                                          RF - - - - - - - -
MII and an and an an
```

Figure 9 (continued)

vehicles. This velocity was computed at the damage centroid and compared for both vehicles. If the velocity difference was less than 10 percent, the average velocity was used as the common velocity. If the difference was more, then the separation velocity for one vehicle was decreased and the other was increased by 10 percent. If the resulting difference, after the adjustment, was less than 10 percent, then the observed warning message (see figure 10) was issued. If the resulting difference were still greater than 10 percent, then a fatal error message would have been issued and execution halted. The purpose of such a check was to disallow an analysis which was not within the scope of the analysis, such as a sideswipe. Both programs performed the above check. However, CRASH3 only reported the condition after two adjustments and did not

ENGINEERING DYNAMICS CORPORATION Date 12-08-1984 Time 12:32:36 RICSAC #7 CHEVELLE V5 RABRIT

WARNING MESSAGES:

Demage-based estimates for Magnitude of Frincipal Force crossly violate Newton's third law of motion. Review the output to determine required corrections to Damage Data and adjust as necessary. The Magnitudes of Frincipal Force for Vehicles I and 2 should be approximately equal.

COMMON VELOCITY WARNING - An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 10 percent.

VEH	10	CL	Ε	٠

IMPACT SPEED MFH	;	SF	PEED CHAN	GE	BASIS OF	
FWD : I	AT :	TOTAL	LONG.	LATERAL	RESULTS	
25.9	0.0	14.8	-13.3	6.5	: SPINOUT TRAJECTORIES A : CONSERVATION OF LINEAR : MOMENTUM	
0.0	0.0	0.0	0.0	0.0	SPINOUT TRAJECTORIES A DAMAGE	ND
		19.7	17.1	7.9	: DAMAGE DATA ONLY	

VEHI	CLE	2

		ACT EED PH	:	SPEED CHAP MPH	4GE	BASIS OF RESMITS
FI	WΙ	LAT	: TOTAL	: LONG.	LATERAL	
5	4.7	. 0.0	32.1	-26.7	17.9	: SPINOUT TRAJECTORIES AND : CONSERVATION OF LINEAR : MOMENTIJM :
; ,	ø. ø	9.0	. W. W	0.0	0.0	: SPINOUT TRAJECTORIES AND : DAMAGE
	-		43.0	37.2	21.5	DAMAGE DATA ONLY

..........

OFUTCLE #2

	VEHICLE	#1	VEHICLE	W-2
IMPACT X-POSITION	0.00	FT.	10.70	FT.
IMPACT Y POSITION	9.00	FT.	3.45	FT.
IMPACT HEADING ANGLE	2.20	DEG.	117.99	DEG.
	64.50	FT.	22.90	FT.
REST X-FOSITION	18.20		41,40	FT.
REST Y-POSITION REST HEADING ANGLE	16.50		261.97	DEG.
END-OF-ROTATION × POSITION	0.00	FI.	22.00	FT.
END-OF- ROTATION Y-POSITION	0.00	FT.	30.00	FT.
END OF ROTATION HEADING ANGLE	0.00	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF ROTATION	360		< 36€	

[MPALI	INFORMAT	IUN		
	VEHICL	E #1	VEHICLE	#2
IMPACT X-POSITION		FT.	10.7	FT.
IMPACT / + DSITION IMPACT HEADING ANGLE	v. 0	FI. DEG.	120.0	DEG.
IMPACT ANGULAR ROTATION RATE	0.0	DEG/SEC DEG.	0.0 0.0	DEG/SEC DEG.
SEPARATION X POSITION	0.0	FT.	10.7	
SEFARATION Y-POSITION	0.0	FT.		
SEPARATION HEADING ANGLE	0.0	DEG.	120.0	DEG.
SEPARATION FORWARD VELOCITY	12.7		8.₽	MFH
SEPARATION LATERAL VELOCITY		MPH	-17.9	MPH
SEPARATION ANGULAR ROTATION RATE	0.0	DEG/SEC	171.7	DEG/SEC

IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)

		FURWARD	CHIENNE
VEH	. 1	25.9 MFH	Ø,Ø MPH
VEH	#2	34.7 MPH	Ø.Ø MFH

VEH #		DAMAGE) LONG. -17.1 MPH 37.2 MPH	LAT. 9.9 MPH -21.5 MPH	ANG. -30.0 DEG. 30.0 DEG.
VEH #	TOTAL	LINEAR MOMENTUM) LONG, -13.3 MPH -26.7 MPH	LAT. 6.5 MPH -17.9 MPH	ANG. -26.1 DEG. 33.9 DEG.

ENERGY DISSIPATED BY DAMAGE: VEH #1 23188.8 FT-LB VEH #2 196487.1 FT-LB

Figure 10 - EDCRASH results with RICSAC7 input

RELATIVE VELOCITY DATA

SFEED ALONG	LINE THRU CGS	(LINEAR MOMENTUM)
VEH #1	24.7 MPH	
VEH #2	7.3 MEH	

SPEED ORTHOG. TO CG LINE (LINEAR MOMENTUM) VEH #1 8.0 MPH VEH #2 33.9 MPH

CLOSING VELOCITY (LINEAR MOMENTUM) 31.9 MPH

SUMMARY OF DAMAGE DATA NOTE: "**" indicates default value

	VEHICLE #1	VEHICLE #2
CLASS (SIZE) CATEGORY	4	2
WEIGHT	3700.0 LBS.	1700.0 LBS.
CDC	11FDEW1	Ø2RDEW4
DAMAGE WIDTH	66.0 IN.	108.5 IN.
CRUSH DEFTH 1	0.0 IN.	Ø.Ø IN.
CRUSH DEPTH 2	1.3 IN.	11.0 IN.
CRUSH DEPTH 3	2.0 IN.	17.B IN.
CRUSH DEPTH 4	3.8 IN.	21.ø IN.
CRUSH DEPTH 5	5.0 IN.	21.3 IN.
CRUSH DEFTH 6	a. 3 IN.	7.3 IN.
DAMAGE MIDPOINT OFFSET	4. Ø IN.	8.5 IN.
DAMAGE ENERGY	23188.8 FT. LB.	1964B7.1 FT. LB.
MAGNITUDE OF PRINCIPAL FORCE	34913.4 LB.	24649Ø.9 LB.
	30.0 DEG.	30.0 DEG.
DIRECTION OF PRINCIPAL FORCE		22.2 IN.
MOMENT ARM OF PRINCIPAL FORCE	61.8 IN.	1.3 IN.
DAMAGE CENTROID	15.6 IN.	1

DIMENSIONAL, INERTIAL AND TIRE/ROAD PROPERTIES

	VEHICLE #1	VEHILLE #1
CG TO FRONT AXLE	54.7 IN.	46.3 IN.
CG TO REAR AXLE	59.2 IN.	50.1 IN.
TRACK WIDTH	61.8 IN.	54,6 IN.
YAW MOMENT OF INERTIA	35822.2 LB-SEC 2-IN	12983.2 LB-SEC-2-IN
MASS	9.6 LB-SEC^2/IN	4.4 LB-SEC^2/IN
BODY LENGTH FROM CG TO FRONT	78.0 IN.	83.3 IN.
BODY LENGTH FROM CG TO REAR	-114.0 IN.	-91.6 IN.
BODY WIDTH	77.0 IN-	67.2 IN.
	ROLLING RESISTANCE	
RIGHT FRONT LIRE	Ø. Ø1	0.01
LEFT FRONT TIRE	0.01	0.01
RIGHT REAR TIRE	ø. 2ø	1.00
LEFT REAR TIRE	0.20	0.20
TIRE/ROAD FRICTION	4.87	W.B7

Figure 10 (continued)

issue a fatal error in the event the common velocity assumption was not satisfied.

The next difference between the programs was found in the IMPACT SPEEDS AND SPEED CHANGES. This difference depended on the CRASH3 code which was used and only occurred if the post-impact path for vehicle #2 had an endof-rotation position. It was due to an error in subroutine START2, wherein the separation coordinates for vehicle #2 were incorrectly assigned the end-of-rotation coordinates rather than the impact coordinates:

> 5 XCSP=XC12 YCSP=YC12

> > should be

5 XCSP=XC2Ø YCSP=YC2Ø

The only other difference was found in the SUMMARY OF DAMAGE DATA section of output, described earlier. Reporting the Magnitude of Principal Force was useful when an error message indicated there was a gross difference in vehicle damage data (figure 10).

After the preliminary output was reviewed, a rerun was performed and a trajectory simulation was requested. The response time for a CDC-Cyber computer was 4.5 seconds. The processing time for the IBM PC was 239.3 seconds. (Only the abbreviated results are displayed.)

SUMMARY OF CRASHS RESULTS

```
RICSAC #7 CHEVELLE VS HABBIT

IMPACT SPEED (IRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD
CATERAL
VEH#1 28.6 MPH .# J#FH
VEH#2 49.2 MPH .# MPH

SPEED CHANGE (DAMAGE)
1016L LONG. LAT. ANG.
VEH#1 17.7 MPH -17.1 MPH 9.9 MPH 2#.0 MEG.
VEH#1 17.7 MPH -17.1 MPH 21.5 MPH 3#.0 MEG.

SPEED CHANGE (LINEAR MOMENTUM)
1016L LONG. CAT. ANG.
VEH#1 17.8 MPH 105.4 MPH 21.5 MPH 2#.0 MEG.
VEH#1 17.8 MPH 25.0 MPH 27.5 MPH 27.5 MPH 28.0 MEG.

ENERCY DISSIPATED BY DAMAGE VEH#1 27.1 MPH 29.5 DEG.

ENERCY DISSIPATED BY DAMAGE VEH#1 21.88 MPT 18 VEH#2 176485.9 FT-L8
SPEED ALONG LINE THRU CUS (LINEAR MOMENTUM)
VEH#1 17.5 MPH 27.5 MPH
VEH#1 17.5 MPH 27.5 MPH 28.0 MPM 29.5 DEG.

SPEED ALONG LINE THRU CUS (LINEAR MOMENTUM)
VEH#1 18.1 MPH
SPEED ORTHOO. TO CU LINE (LINEAR MOMENTUM)
VEH#1 38.4 MPH
VEH#1 38.4 MPH
VEH#1 37.4 MPH 37.4 MPM 37.4 MPM
```

TRAJECTORY SIMULATION RESULTS

		# 1 DID NOT CONVERGE # 2 CONVERGED O.F. C			
NEUNS (1)		5	NRUNS (2)	*	5
E1(1)	-	. 273	E2(1)	*	. 267
E1(2)		. ଅନ୍ତଳ	E2(2)	=	.007
E1 (3)		1.020	E2 (3)	=	. 860
E1(4)	-	. 860	E2(4)	-	042
E1(5)	=	. 300	£2(5)	25	المائية الراء
QMIN1	=	1.292	UMIN2	=	.191

Figure 11 - CRASH3 results for RICSAC7 with a trajectory simulation

Inspection of the output results (CRASH3, figure 11; EDCRASH, figure 12) again revealed a difference in IMPACT SPEEDS AND SPEED CHANGES. The difference was due to two different sources: (1) the end-of-rotation error, and (2) increasing the integration time interval from 0.025 to 0.100 seconds. Each of these differences has been described earlier. The effect of increasing the integration time step has been shown to be minor (refer to figures 6 and 7). The major cause of the difference was the end-or-rotation error, which provided the trajectory simulation a substantially different set of initial velocities (especially angular velocity; see figures 9 and 10, Separation Conditions).

SUMMARY OF EDCRASH RESULTS

ENGINEERING DYNAMICS CORFORATION Date 12 08-1984 Time 12:50:02
RICSAC #7 CHEVELLE VS RABBIT

WARNING MESSAGES:

Damage-based estimates for Magnitude of Principal Force grossly violate Newton's third law of motion. Review the output to determine required corrections to Damage Data and adjust as necessary. The Magnitudes of Principal Force for Vehicles 1 and 2 should be approximately equal.

COMMON VELOCITY WARNING -- An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 10 percent.

RELATIVE VELOCIT/ DATA

SPEED ALONG LINE THRU CGS (LINEAR MOMENTUM)
VEH #1 28.0 MPH
VEH #2 11.3 MPH
SPEED ORTHOG. 10 CG LINE (LINEAR MOMENTUM)
VEH #1 -9.0 MPH
VEH #2 52.5 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
39.3 MPH

TRAJECTORY SIMULATION RESULTS

++++VEHICLE # 1 DID NOT CONVERGE ++++
++++ VEHICLE # 2 CONVERGED OF ++++

NUMBER OF RUNS (MAXIMUM OF 5) 5	2
REST POSITION X-1 ERROR (:=.10) 0.26	5 0.093
END OF-ROTATION X-Y ERROR (=.15) Ø. 88	ø. 115
REST POSITION HEADING ERROR (=. 10) 1.030	8 4.418
END-OF-ROTATION HEADING ERROR (= . 15) #. ##	e -0.150
POINT-ON-CURVE X-Y ERROR (=.15) Ø. ØØ	0.000
TOTAL WEIGHTED ERROR SUM 1.300	2 0.243

Figure 12 - EDCRASH results for RICSAC7 with a trajectory simulation

For purposes of illustration, another rerun was performed and the trajectory simulation option was turned off. Then, the post-impact trajectory of vehicle #1 was changed so that it was curved. Both programs modelled the curved path by assuming the path was defined by a circle. The position of vehicle #1 at impact and rest defined two points on the circle, and required a third point to be supplied by the user. This point allowed the radius (which was assumed to be constant) of the path and the path length to be calculated. In addition, it allowed the separation (i.e., post-impact) angle to be based on the curved path, rather than the straight line between impact and rest positions. This feature was extremely important, since the separation angle had a great effect on separation velocity. In order to use this feature, a point on the curved path was entered:

Point on curve = 40,4

RICSAC #7 CHEVELLE VS RARRIT

SUMMARY OF RESULTS

1 mi		TRAJECTORY AND	CONSERVATION	OF LINEAR I	MOMENT UM
	FORWARD	LATERAL			
VEH#1	26.2 MPH	.Ø MPH			
VEH#2	35.0 MFH	.Ø MFH			
5F8	EED CHANGE	(DAMAGE)			
	10THL	LONG.	LAI.	-DM-	
VEH#1	19.7 MPH	-17.1 MEH	9.9 MPH	-30.0 DEG.	
VEH#2	43.0 MFH	-37.2 MfH	21.5 MPH	30.0 DEG.	
SFE	EED CHANGE	*LINEAR MOMENTU	MI.		
	10 Test	LONG.	LA1.	ealáís.	
VEH#1		-10.5 MPH			
		27.0 MFH			
ENERGY	DISSIPATED	BY DAMAGE VEH	#1 23189.8 F	T-LB VEH#2	196486.9 FT-I

RELATIVE VELOCITY DATA

SPEED ALONG	LINE THRU COS (LINEAR MOMENTUM)
VEH#1	25.0 METH
VEH#1	7.5 MPH
SPEED ORTHOG	. TO CO LINE (LINEAR MOMENTUM)
VEH#1	-8.1 MF11
VEH#2	54.2 MPH
CLOSING MELD	CITY (LINEAR MUMENTUM)
	32.3 MPH

SCORE INFURMATION

	MENTICEE #	1	VEHICLE #	2
DIFACT K FOSITION	ويزان	FT.	10. 9	F-T.
IMPACT - FOSITION	. 44.1	Et.	5, 45	F 1.
IMPACT HEADING ANGLE	.140	IÆ€.	119.79	DEU.
REST & FOCITION	84.56	F 1.	and 101	£1.
REST : FOSTION	113.129	f1.	41.40	FT.
REST HEADING ANGLE	10.50	DEG.	261.97	DEG.
END-OF ROTATION *-FOSTITION	. 0.0	F1.	22.00	F1.
END OF EGIATION : FOULTION	.0,1	51.	3.9 , 1141	1.1.
END OF ROTALION HEADING ANGLE	. 1963	DEL.	149.91	Lt.ii.
FOINT ON CURVE & POSITION	40.00	FT.		
FOINT-ON-CURVE Y-FOSITION	4.1161	F 1.		
Disection Of Roletton	, w		(N	
AMOUNT OF POTATION	160		750	

Figure 13 - CRASH3 results with point on curve

These results (CRASH3, figure 13; EDCRASH, figure 14) have been limited to the abbreviated listing plus the echo of scene data, which displays the user-entered point on curve.

Inspection of the results again revealed a difference in IMPACT SPEEDS AND SPEED CHANGES, due only to the end-of-rotation error.

In order to investigate another feature related to curved post-impact trajectories, the point on curve was changed:

Point on curve = 40.8.5

The results (CRASH3, figure 15; EDCRASH, figure 16) revealed the IMPACT SPEEDS AND SPEED CHANGES were the same as those obtained without a point on curve. This intentional result was caused by the selection of a point which was on the straight line between impact and rest positions. EDCRASH issued an informative message indicating this was the case. Note the echo of scene data did not include the user-entered point on curve. This circumstance would not lead to erroneous results.

ENGINEERING DYNAMICS COPPORATION Date 12:00 1404 State 12:55:27 RICHARD BY CHEVELLE 15 MADELE

WARNING MESSAGES:

Damagentiased estimates for Mignitude of Principal Porce grossly violate Newton's third law of motion. Seview the output to determine required corrections to Damage Date and adjust as incessor.

The Magnitudes of Principal Force for Venicles 1 and 1 should be approximately again.

COMMON VELOCITY WARNING — An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed by percent.

IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)

FORWARD LATERAL

VEH #1 20.0 MFH 0.0 MFH

VEH #2 20.1 MFH 0.0 MFH

SPEED CHANGE (DAMAGUE)

TOTAL LONG. LAT. ANG.

VEH #1 19.7 MFH -17.1 MFH 9.7 MFH -20.0 DEG.

SPEED CHANGE (LINEAR MOMENTUM)

TOTAL LONG. LAT. ANG.

VEH #1 14.0 MFH -17.1 MFH -21.5 MFH 30.0 DEG.

SPEED CHANGE (LINEAR MOMENTUM)

TOTAL LONG. LAT. ANG.

VEH #1 14.0 MFH -17.5 MFH -5.5 MFH -20.1 DEG.

VEH #1 12.3 MFH -17.5 MFH -5.5 MFH -20.1 DEG.

ENERGY DISSIFATED BY DAMAGE: VEH #1 27188.8 FT-LB VEH #2 196481.1 FT-LB

RELATIVE VELOCITY DATA

SPEED ALONG LINE THRU COS :LINEAR MOMENTUM:
VEH #1 24.7 MPH

SPEED ORTHOG. TO CO LINE (LINEAR MOMENTUM)
VEH #1 - 6.0 MPH
VEH #2 -33.7 MPH

CLOSING VELOCITY (LINEAR MOMENTUM)
32.0 MPH

SCENE INFORMATION

	VEHICLE	# 1	VEHICLE	#2
IMPACT X-POSITION	0.00	FI.	10.70	FT.
IMPACT Y-FOSITION	4.00	FT.	5.45	FT.
IMPACT HEADING ANGLE	0.00	DEG.	119.97	DEG.
REST X-FOSITION	84.50	FT.	22.90	FT.
REST Y-FOSITION	18.00		41.40	F.F.
REST HEADING ANGLE	16.50		261.97	DEG.
END OF ROTATION X FUSITION	0.00	F I.	22.00	fT.
END OF ROTATION Y PUSITION	0.00	ET.	30.00	FT.
END-OF-ROTATION HEADING ANGLE	0.00		249.97	DEG.
FDINT DN CURVE X POSITION	40.00			
POINT ON CURVE Y-POSITION	4.00	ET.		
DIRECTION OF POTATION	CW		€₩	
AMOUNT OF BOTATION	Tord		269	

Figure 14 - EDCRASH results with point on curve

Another condition was found which could cause misleading results, however. In order to illustrate this potential for error, the point on curve was again changed:

Point on curve = 40.85

The results (CRASH3, figure 17; EDCRASH, figure 18) revealed a significant difference for IMPACT SPEEDS AND SPEED CHANGES. The difference was caused by entering an errant point on curve (i.e., one which was too far away from the impact and rest positions to lie within the smallest possible circle drawn through the points which define the impact and rest positions). This was also the cause of the common velocity warning message issued by CRASH3 (figure 17).

RICSAC #7 CHEVELLE VS RAPRIT

SUMMARY OF RESULTS

	IMPACT SPEED	CTRAJECTORY AND	CONSERVATIO	N OF LINEAR MOMENTUM	
	FORWARD	LATERAL			
VEH#	1 26.1 MPH	. e MFHI			
VEH#	2 34.9 MFH	. e MEH			
	SPEED CHANGE	(DAMAGE)			
	TOTAL	LONG.	LAT.	ANG.	•
VEH#	1 19.7 MPH	-17.1 MPH	9.9 MPH	-30.0 DEG.	
VEH#.	2 43.6 MPH	-37.2 MPH	21.5 MPH	Ta. # DEG.	
	SPEED CHANGE	(LINEAR HOMENT	JM)		
	TOTAL	LONG.	LAT.	ANG.	
VEH#	1 15.0 HFH	-13.5 MFH	6.5 HFH	-25.6 DEG.	
VEH#	2 32.7 MPH	27.0 MPH	18.4 MPH	34.4 DEG.	

ENERGY DISSIPATED BY DAMAGE VEHW1 23188.8 FT-LB VEHW2 196486.9 FT-LB

RELATIVE VELOCITY DATA

SPEED ALONG LIME THRU CGS (LINEAR MOMENTUM)
VEH01 24.9 HPH
VEH02 7.3 NPH
SPEED ORTHOG, IO CG LINE (LINEAR MOMENTUM)
VEH01 8.0 HPH
VEH02 -34.2 MPH
CLOSING VELOCITY (LINEAR MOMENTUM)
32.2 HPH

SCENE INFORMATION

	VEHICLE #	ı	MENICLE #	2
IMPACT X-POSITION	. 00	FT.	10.70	FT.
IMPACT Y-POSITION	. 00	FT.	3.45	
IMPACT HEADING ANGLE	. 00	DEG.	117.99	DEG.
REST X-POSITION	84.50	FT.	22.90	FT.
REST Y-POSITION	18.20	Fī.	41.48	FT.
REST HEADING ANGLE	16.50	DEG.	261.97	DEG.
END-OF-ROTATION X-FUSITION	.00	FI.	22.00	FT.
END-OF-ROTATION Y-FUSITION	. હોલ્ટી	f1.	30, 40	FI.
END-OF-ROTATION HEADING ANGLE	. 00	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CM		CW	
AMOUNT OF ROTATION	366		360	

Figure 15 - CRASH3 with a point on curve which was on a straight line between impact and rest

No other significant differences relating to the calculations were identified.

Graphics

EDCRASH produced a graphical output called a Site Drawing (figure 19). The display was limited to the vehicle outlines shown in plan view and placed at the user-entered impact and rest positions. A vehicle was also displayed at the end of rotation if one was entered. If a point on curve was entered, it was displayed only as an x-y point, since a PSI (heading angle) value was not supplied, and the orientation of the vehicle was not established.

The vehicle dimensions were based on the user-entered size (class) categories. The scale of the accident site was established from the minima and maxima of the impact and rest positions.

Output data was also displayed. This output was limited to impact speeds, and positions at impact and rest.

Additional details, including titles, headings, and other results, were added by typing the desired information onto the display.

ENGINEERING DYNAMICS CORPORATION Date 12-89-1984 Time 12:17:44
RICSAC 87 CHEVELLE VS RABBIT

WARNING MESSAGES:

Damage-based estimates for Magnitude of Principal Force grossly violate Newton's third law of motion. Review the output to determine required corrections to Damage Date and adjust as necessary. The Magnitudes of Principal Force for Vehicles 1 and 2 should be approximately equal.

User entered point on curve for vehicle #1 was discarded because the position was practically on a straight line between impact and rest. If the post-impact path was curved and your point on curve was rejected the results may be erroneous. Check your data.

COMMON VELOCITY WARNING -- An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not exceed 1θ percent.

	ΙM	ACT SPEED	(TRAJECTORY AND	CONSERVATION (OF LINEAR MOMEN	TUM!
		FORWARD	LATERAL			
VEH	• 1	25,9 MPH	Ø.Ø HPH			
VEH	#2	34.7 MPH	0.0 MPH			
	SPE	ED CHANGE	(DANAGE)			
		TOTAL	LDNG.	LAT.	ANG.	
VEH	.1	19.7 MPH	-17.1 MPH	9.9 MPH	-30.0 DEG.	
VEH	#2	43,0 MFH	-37.2 MPH	21.5 MPH	30.0 DEG.	
	SPE	EED CHANGE	LINEAR MOMENTU	M)		
		TOTAL	LONG.	LAT.	ANG.	
VEH	.1	14.8 MFH	-13.3 MPH	6.5 MFH	-26.1 DEG.	
VEH	02	32.1 MPH	26.7 MPH	-17.9 MPH	33.9 DEG.	
ENEF	RGY	DISSIPATED	BY DAMAGE: VE	H #1 23188.8	FT-LB VEH #2	196487.1 FT-LB

RELATIVE VELOCITY DATA

VEH #1	INE THRU CUS	(LINEAR MOMENTUM)
VEH #2	7.3 MPH	
SPEED URTHOG.	TO CO LINE	(LINEAR MOMENTUM)
VEH #1	B. Ø MFH	
VEH #2	33.9 MFH	

SCENE INFORMATION

	VEHICLE	*1	VEHICLE	#2
IMPACT X-POSITION	0.00	FT.	10.70	FT.
IMPACT Y POSITION	0.00	FT.	3.45	FT.
IMPACT HEADING ANGLE	0.00	DEG.	119.99	DEG.
REST X FOSTITION	84.50	61	22.90	FT.
REST Y-POSITION	18.19		41.40	FT.
REST HEADING ANGLE	16.50	DEG.	261.97	DEG.
END-OF-ROTATION X POSITION	0.00	FI.	22.00	FT.
END OF ROTATION Y POSITION	છે. છેલે	FT.	30.00	FT.
END OF ROTATION HEADING ANGLE	4.00	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CW		CW	
AMOUNT OF ROTATION	364		360	

Figure 16 - EDCRASH with a point on curve which was on a straight line between impact and rest

CONCLUSIONS

- 1. The CRASH program, either EDCRASH or CRASH3, represented an effective means of reconstruction for most single- and two-vehicle accidents.
- 2. EDCRASH and CRASH3 required the same input data.
- 3. EDCRASH produced additional output when compared to CRASH3, including the Magnitude of Principal Force and Graphics.
- 4. The major difference between EDCRASH and CRASH3 was user-interactivity. This was the result of substantial differences in program design.

WARNING SEPARATION VELOCITIES ALONG DOFF ARE
NOT COMFATICL. ACCORDING TO ASSUMPTION OF A
COMMUN VELOCITY AT THE DAMAGE AREA CENTROIDS.

RICSAC #7 CHEVELLE VS RABBIT

SUMMARY OF RESULTS EMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORWARD LATERAL
(#1 35.7 MPH & MPH
(#2 47.9 MPH & MPH SPEED CHANGE (DAMAGE) LAT. 9.9 MFH 21.5 MFH SPEED CHANGE (LINEAR MOMENTUM) LUNG. 15.8 MPH 36.4 MPH ENERGY DISSIPATED BY DAMAGE MENHI 20188.8 FT-EB MEHH2 196486.9 FT ED RELATIVE VELOCITY DATA

SFEED ALONG LINC THRU COS (LINEAR MOMENTUM)
VEHMA 55.7 HH H
VEHMA 9.2 HHH
SFEED DEFINOG TO CO LINE
VEHMA 10.2 HHH
VEHMA 4.2 HHH
CLOSING VELOCITY (LINEAR HOMENTUM)
47.1 HH H

SCENE INFORMATION

	VEHICLE #	1	VEHICLE *	2
IMPACT Y POSITION IMPACT Y POSITION IMPACT HEADING ANGLE	. ଅନ . ଅଧ . ଅଧ	FT. FT. DEG.	10.70 3.45 119.99	FT. FT. DEG.
MEST / POSITION REST / FOSITION REST MEADING ANGLE	84.58 18.28 16.58		22.90 41.40 261.97	FT. FT. DEG.
END OF ROTATION & POSITION END OF ROTATION & POSITION END OF ROTATION HEADING ABOUT	, ଶଧ ପ୍ରଶ	FT. FT. DEG.	22. 88 58.08 .47.9	F1. F1. DEG.
FOINT ON CHRVE K-FOSITION POINT ON CURVE Y-FOSITION	40.00 85.00			
DIRECTION OF ROTATION AMOUNT OF ROTATION	CM 1368		5.36 0	

Figure 17 - CRASH3 with errant point on curve

- 5. A difference in processing time was identified. The difference was not significant unless a trajectory simulation was requested, wherein a CDC-Cyber mainframe (CRASH3) required 4.5 seconds compared to about 5 minutes for EDCRASH. Without a trajectory simulation, CRASH3 required approximately 1 second while EDCRASH required about 5 seconds.
- 6. EDCRASH and CRASH3 produced different results when the post-impact path for vehicle #2 had an end of rotation. This was the result of an error found in CRASH3.
- 7. EDCRASH and CRASH3 usually produced slightly different results when a trajectory simulation was requested. This was primarily the result of the end-of-rotation error (above).
- 8. EDCRASH and CRASH3 handled the case of a post-impact point on curve differently. EDCRASH performed an additional validity check to help insure valid data and corresponding results.
- EDCRASH generated additional warning messages, both informative and fatal, resulting from validity checks for damage data and common

ENGINEERING DINAMICS CORPORATION Date 12 000 1984 Time 12:200:26 PICSAC W7 CHEVELLE 25 FMDEIF

Demons based estimates for Magnitude of Frincipal Force grossl. Fields Beston's third law of motion. Heriow the output to Jotefaure required normalization to Damage Date and adjust as indicases. The Magnitudes of Frincipal Force for Vehicles 1 and 2 should be approximately equal.

User entered point on converter terms of the Web discarded because the position was too har away from other path coordinates to make sense. If the post-impact path was curved and our point or curve was rejected the results may be erruneous. Check your data.

COMMON VELUCITY WARNING — An adjustment of vehicle separation conditions was performed in order to be consistent with the common velocity assumption. The adjustment does not served 18 percent.

```
IMPACT SPEED (TRAJECTORY AND CONSERVATION OF LINEAR MOMENTUM)
FORMAND CATEMAL
VEH #1 15.2 MEM #2.8 MEM
VEH #1 15.2 MEM #2.8 MEM
VEH #1 14.1 MEM #2.8 MEM
    SEEED CHANGE (DAMAGE)
101AL
VEH #1 19.7 MFH
VEH #2 47.0 MFH
                                  LUNG.
-17.1 MFH
-27.2 MPH
      SPEED CHANGE of INFAR MOMENTUM
                                  LONG.
-13.3 MEH
26.7 MEH
ENERG: DISSIFATED E. DAMAGE: VEH #1 | 23188.8 FT LB | VEH #2 | 19648 1.1 FT LB
```

FELSHIVE VELOCITY DATA

SPEEL HOUSE LIN	E THRU LGS (LINEAR MOMENTUM) : 	
.'€.+- # _	1.7 MEH	
	0 CS LINE (LINEAR MOMENTUM)	
E 1 #1		
EH #2	G. Chill	
CLUSING VECOCIT	/ (LINEAR MONENTUM)	
	II.7 MEN	

CCENE	TRECIENCETION	

	VEHICLE	• 1	VEHICLE	•2
IMPACT X-POSITION	3.89	FT.	10.70	FT.
IMPACT (FOSITION	e. 341	FT.	3, 45	FT.
IMPACT HEADING ANGLE	0.00	DEG.	117.99	DEG.
REST & PUSITION	84.50	. 7	21.98	FT.
REST (-FOSTITON	18.00		41.40	FT.
REST HEADING ANGLE	15.50		261.97	DEG.
END OF ROTALION X FOSITION	હા. છેલ	FT.	22.00	FT.
END OF ROTATION / POSITION	ot aller	Ft.	30.00	F.F.
END OF -ROTATION HEADING ANGLE	0.00	DEG.	249.97	DEG.
DIRECTION OF ROTATION	CW		Ċ₩	
AMOUNT OF ROTATI N	36V		760	

Figure 18 - EDCRASH with errant point on curve

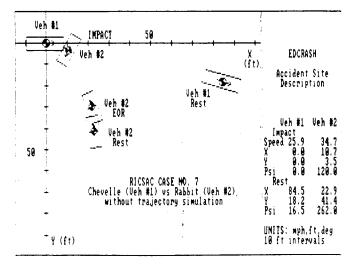


Figure 19 - EDCRASH Site Drawing

velocity to insure valid data and corresponding results.

10. EDCRASH produced a graphics display of the results.

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